

The sea affords Belgium the benefits of marine resources taken in the broadest sense: fishery, tourism, sand and gravel exploitation, but also the dispersive capacity of water bodies permitting the controlled disposal of wastes, and transport routes requiring large harbour infrastructures and maintenance of the navigable channels.

The intensive uses of all these resources have obvious economic impacts. They also interact in a competitive way, and they can affect the natural equilibrium of the marine ecosystem.

In order to ensure an optimal management of these different uses — for which various government departments are responsible — the public authorities utilize the "North Sea and Scheldt Estuary Mathematical Model" that they developed for that purpose.

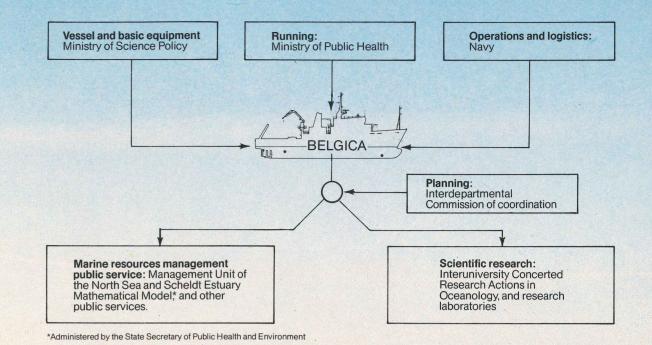
This model is continuously improved by taking benefits from research efforts in oceanology. It allows one to simulate on computer the evolution and impact of the various hydrodynamic, physical, chemical, biological and geological processes that take place in the sea. The model provides, especially through the comparison of various scenarios, objective informations for defining the most suitable management options.

Such informations need to be constantly validated by field observations. The performance of the model itself must be improved through a better understanding of marine processes. The acquisition of oceanographic data, largely automatized, constitutes, therefore, an essential goal of the BELGICA, a public service research vessel.

Besides her public service function, the ship represents a major research tool for the oceanological studies achieved in the North Sea.

The management and protection of the North Sea are implemented thanks to a tight cooperation between all the riverine States. Belgium ratified international conventions that require permanent control and monitoring programmes. The BELGICA enables the efficient fulfilment of such obligations.









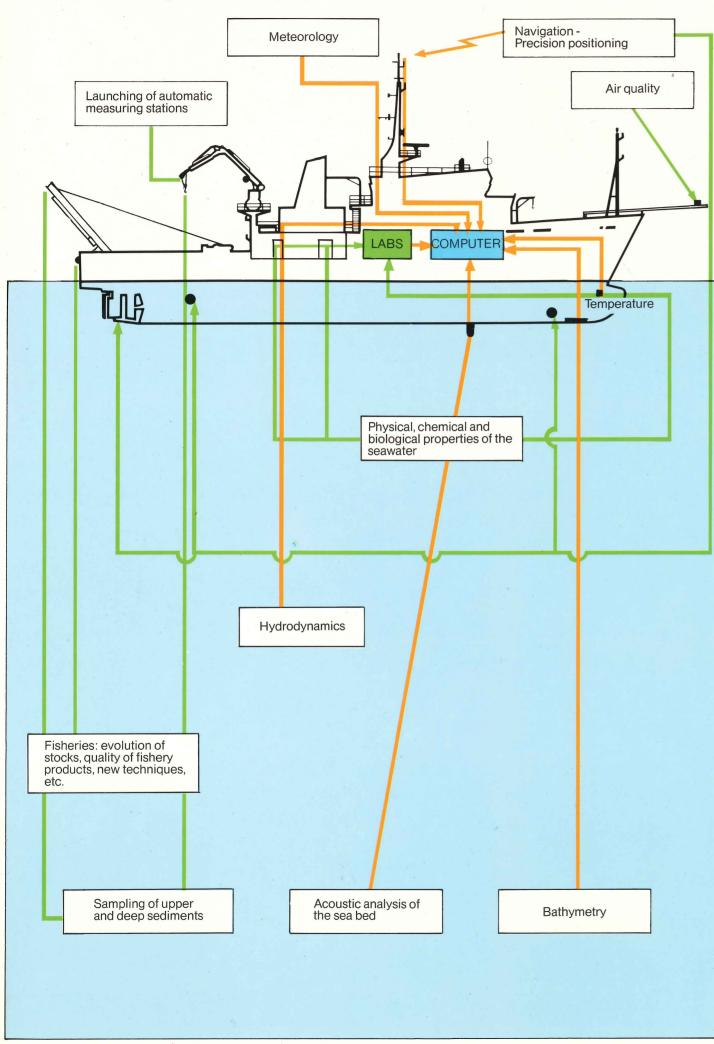






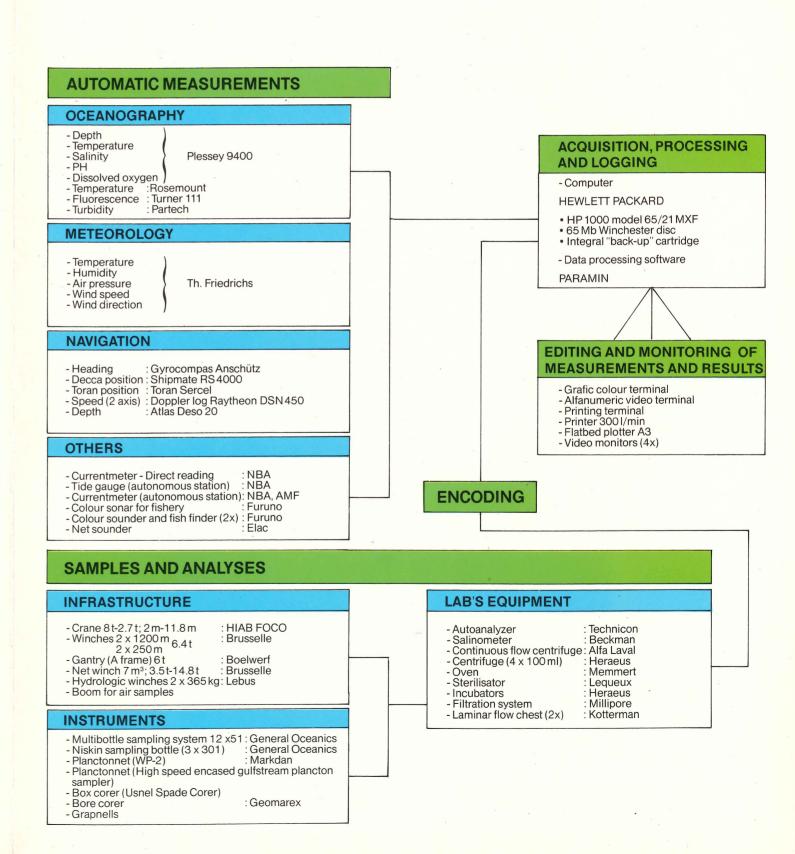


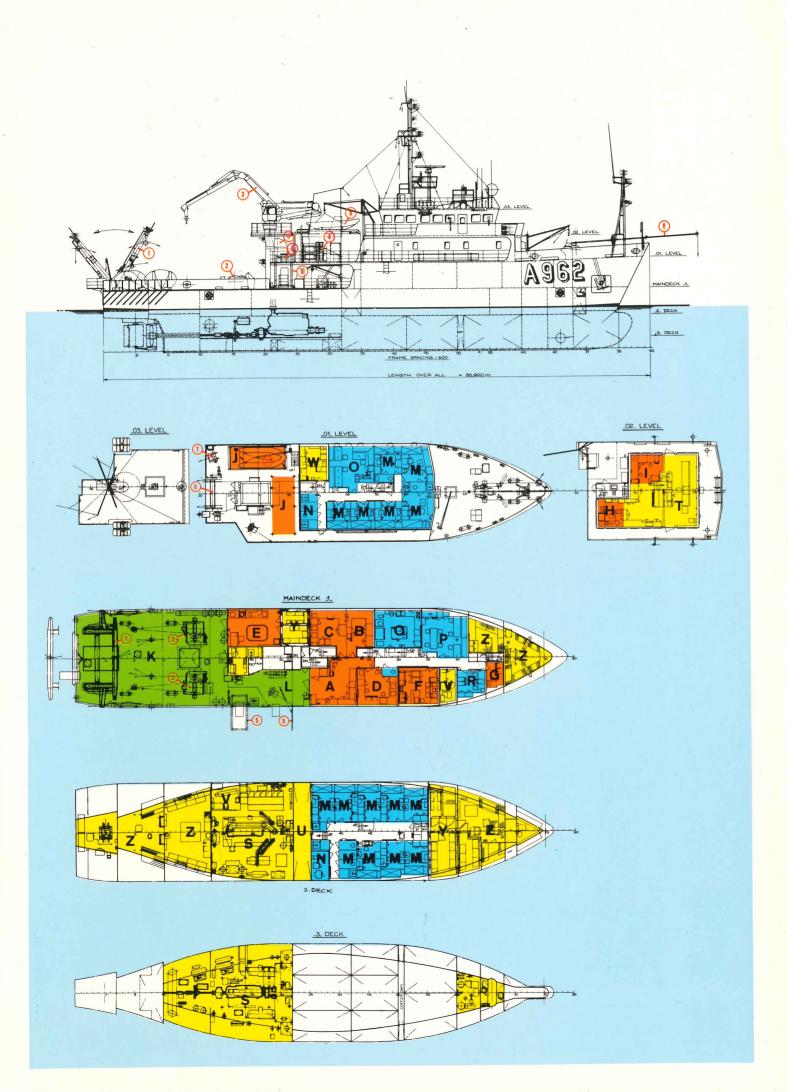
An equipment designed for multipurpose missions



Basic instruments

The basic configuration allows the use of many different instruments for the execution of specific programs.





DECK

- Pivoting gantry
 Main winches
 Telescopic folding crane
 Hydrologic winches
 Gantry and davit for hydrology
 Sliding arm
 Netscunder winch
- 7. Netsounder winch 8. Net winch
- 9. Workboat

SCIENTIFIC SPACES AND LAB'S

- A. Wet lab
 B. Lab for chemistry
 C. Lab for microbiology
 D. Lab for biology
 E. Lab for fishery

- F. Computer room G. Foto lab
- H. Fishery control center
 I. Space for recorders
- J. Container lab

WORK DECKS

- K. After deck: fishery, heavy sampling L. Side deck: light sampling

ACCOMODATION

- M. Cabins
 N. Sanitary
 O. Officer's and scientist's mess
 P. Crew's mess
 Q. Galley
 R. Ship's office

TECHNICAL DEPARTMENT, WORKSHOPS, STORES, REFRIGERATING ROOMS

- S. Engine room
 T. Wheelhouse
 U. Stabilizing tank
 V. Workshops
 W. Radio room

- Diver's room
- Refrigerating rooms
- Stores

COMPLEMENT

Staf and crew: 15 Scientists: 12

MAIN CHARACTERISTICS

50.900 m 48.650 m 10.000 m 3.200 m 5.700 m Over all length Length between perpendiculars Beam Depth to tweendeck Depth to main deck 4.402 m Draught Water displacement 1,192 t 765 t Gross tonnage

CLASSIFICATION

"Germanischer Lloyd's + 100 A4 + MC AUT 16/24 Research Vessel"

Build by BOELWERF, Temse, Belgium

MACHINERY

Main propulsion unit

One 6 cylinder, four stroke, turbo charged "ABC6 DZ" medium speed diesel engine (1030 rpm) driving a controllable pitch

Maximum continuous output at 360 rpm propeller

speed

1154 kW

Auxiliary propulsion

Two transverse thrusters (bow and stern) hydraulically 2x150kW

Electric plant

Two diesel driven alternators 2x275kW One static converter/regulator (220 V \pm 1% and 30kVA $50 \text{ Hz} \pm 0.5\%$

Hydraulic plant

The various deck machinery, gantries, winches, etc., are powered by an extensive hydraulic power plant consisting of:

- two main hydraulic pumps driven by the main engine - four auxiliary hydraulic pumps driven by electric motors

Deck machinery

1 electric anchorrage winch combined to the mooring winch7.5 t 2 combined trawling-fishing winches $7 \, \text{m}^3 / 5 \, \text{t}$

1 fishing netdrum 2 hydrological winches

1 net sounder winch

1 stern gantry 1 folding/telescopic hydraulic crane

8t 2t at 11 m 8tat2m

LABORATORIES AND EQUIPMENTS

Surface or capacity and particular equipments of the laboratories		
WET LAB	20 m²	Storage and rinsing of sampling instruments. Frigo. Deep freezer. Fresh water distillator.
LAB I biology	12 m²	Cardan table. Labo centrifuge. Fume extractor.
LAB II microbiology	12 m²	Cardan table. Laminar flow cabinet. Incubators. Autoclave. Oven.
LAB III chemistry	10 m²	Cardan table. Laminar flow cabinet. Nutrient autoanalyzer.
FISH LAB	20 m²	Fish tank. Fish "throw away" tube. Cardan table.
FOTO LAB	4 m²	Special lightning.
COMPUTER ROOM	14 m²	Data acquisition and processing computer system.
CONTAINER LABS	13 m²	Basic laboratory infrastructure in standard 20 ft container.
WHEEL HOUSE	45 m²	Navigation instruments. Echo sounders. Recorders. Meteo station. Fish detection instruments. Remote winches control.
COOL CHAMBRES	14 m³	Temperature −25°C and 0°C.

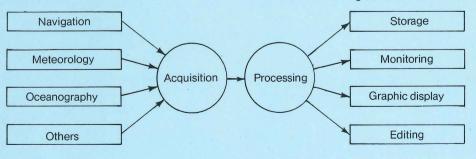
INSTRUMENTATION

Dual axisdoppler log RAYTHEON DSN 450 Gyrocompas ANSCHUTZ STD 12 Navigation instruments SHIPMATE RS 4000 Positioning system TORAN PH Dual frequency echo sounder ATLAS DESO 20 Meteo station TH FRIEDRICHS Fish detection instruments FURUNO Net sounder ELAC Nutrient autoanalyzer TECHNICON

CTD, PH, O₂ Multiprobe PLESSEY Salinometer BECKMAN Continuous flow fluorimeter TURNER 111 Turbidity meter PARTECH Water purifier ALFA LAVAL Rosette water sampler GENERAL OCEANIC Bore corer GEOMAREX Box corer USNEL SPADE CORER Direct reading currentmeter NBA

Data acquisition and processing computer system DAPCOS

The main functions of the DAPCOS are summarized in the figure hereunder:



The computer system is based on a HEWLETT PACKARD HP1000 CPU with a WINCHESTER disc 65 Mb memory, a magnetic tape cartridge "back-up," 2 video terminals, 2 printers, 1 plotter and 4 video display monitors. The User Software has been developed in collaboration with "PARAMIN N.V."

